

CHAPTER 1

BASIC CONCEPTS

Iris Hui-Ru Jiang

Basic Concepts

□ Contents

- ▣ System life cycle
- ▣ Object-oriented design
- ▣ Data abstraction and encapsulation
- ▣ Algorithm specification
- ▣ Performance analysis and measurement

□ Readings

- ▣ Chapter 1
- ▣ C++
 - H. Deitel and P. Deitel, C++ How to Program, 5th Ed., Prentice Hall, 2005. ISBN: 0131971093.

System Life Cycle

Hierarchical
approach

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- **Regard a large-scale computer program as a system**
 - Programming >> coding
- 1. **Requirements**
 - Define **specifications** (input and output): vague → rigorous
- 2. **Analysis**
 - Divide into manageable pieces: **top-down** vs. bottom-up
- 3. **Design**
 - Determine data objects (abstract data types) and operations (algorithms): **language-independent**
- 4. **Refinement and coding**
 - Implement: **language-dependent**
- 5. **Verification**
 - Correctness proofs: use formal (mathematics) techniques
 - Testing: include all possible scenarios; estimate performance
 - Error removal: debug based on above two; avoid **spaghetti** codes

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Object-Oriented Design

Algorithmic vs. OO Decomposition...



Divide
-and-
Conquer

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- **Algorithmic (functional) decomposition** views software as **a process**
 - ▣ Decompose the software into **steps**
 - ▣ **Data structures** are a secondary concern
- **Object-Oriented decomposition** views software as **a set of well-defined objects**
 - ▣ Model entities in the application domain
 - ▣ Interact with each other to form a software system
 - ▣ **Functional decomposition** is addressed after the system has been decomposed into objects
- **Advantages of OO decomposition:**
 - ▣ Encourage **reuse** of software
 - ▣ Allow software to evolve as system requirements change
 - ▣ Is more intuitive: objects naturally model entities in the application domain

Object-Oriented Programming

- **Definition: An **object** is**
 - ▣ An entity that performs computations and has a local state
 - ▣ $\Rightarrow$ Viewed as a combination of data and procedural elements
- **Definition: **Object-oriented programming** is a method of implementation in which**
 1. **Objects** are the fundamental building blocks
 2. Each object is an instance of some type (or **class**)
 3. Classes are related to each other by **inheritance** relationships
- **Definition: An **object-oriented language****
 1. Supports **objects**
 2. Requires objects to belong to a **class**
 3. Supports **inheritance**
- **The first two features are considered as **object-based****

7 Data Abstraction and Encapsulation

Example: DVD Players

- **Packaging:** Control panel (remote control) of a DVD player:



- Interact only through buttons
- **Encapsulation:** hide **internal representation** from users
- **Usage:** Instruction manual of the DVD player
 - Does tell us **what** the DVD player does
 - **Abstraction:** describe **what** to do, not **how** to do

Data Abstraction & Encapsulation

- **Definition: Data encapsulation (information hiding)**

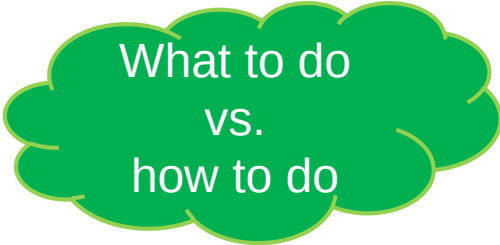
- Conceal the **implementation details** of a data object from the outside world



Make a data
object as a
black box

- **Definition: Data abstraction**

- Separate the **specification** of a data object and its **implementation**



What to do
vs.
how to do

Data Type

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- **Definition: A data type is**

1. A collection of **objects**, and
2. A set of **operations** that act on those objects

- **Example: int**

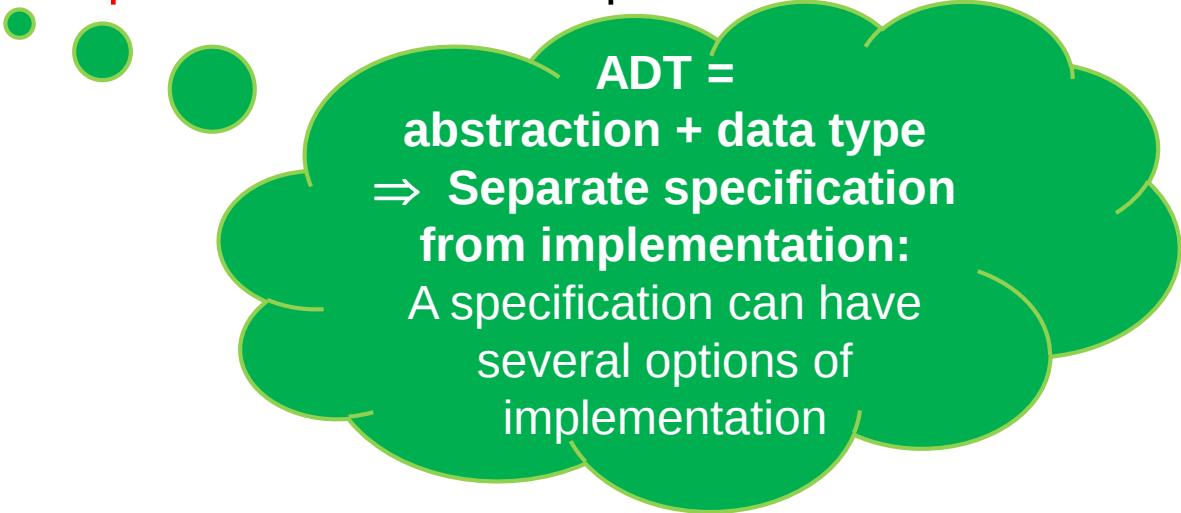
1. Objects: $\{0, +1, -1, +2, -2, \dots, \text{MAXINT}, \text{MININT}\}$
 - **MAXINT**: maximum integer on the computer
 - **MININT**: minimum
2. Operations: $\{+, -, *, /, \%, \ll, \gg, ==, !=, \dots\}$

Abstract Data Type (ADT)

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- **Definition:** An **abstract data type (ADT)** is
 - ▣ A data type
 - ▣ The **specification** of the **objects** is separated from the **representation** of the objects
 - ▣ The **specification** of the **operations** on the objects is separated from the **implementation** of the operations



ADT =
abstraction + data type
⇒ Separate specification
from implementation:
A specification can have
several options of
implementation

ADT Example: *NaturalNumber*

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ADT *NaturalNumber* is

objects: An ordered subrange of the integers starting at 0, ending at MAXINT on the computer.

functions:

for all $x, y \in \text{NaturalNumber}$; $\text{TRUE}, \text{FALSE} \in \text{Boolean}$
and where $+$, $-$, $<$, $==$, and $=$ are the usual integer operations

<i>Zero(): NaturalNumber</i>	::=	0
<i>IsZero(x): Boolean</i>	::=	if (x == 0) <i>IsZero</i> = TRUE else <i>IsZero</i> = FALSE
<i>Add(x, y): NaturalNumber</i>	::=	if (x+y <= MAXINT) <i>Add</i> = x + y else <i>Add</i> = MAXINT
<i>Equal(x, y): Boolean</i>	::=	if (x == y) <i>Equal</i> = TRUE else <i>Equal</i> = FALSE
<i>Successor(x): NaturalNumber</i>	::=	if (x == MAXINT) <i>Successor</i> = x else <i>Successor</i> = x + 1
<i>Subtract(x, y): NaturalNumber</i>	::=	if (x < y) <i>Subtract</i> = 0 else <i>Subtract</i> = x - y

end *NaturalNumber*

::= is defined as

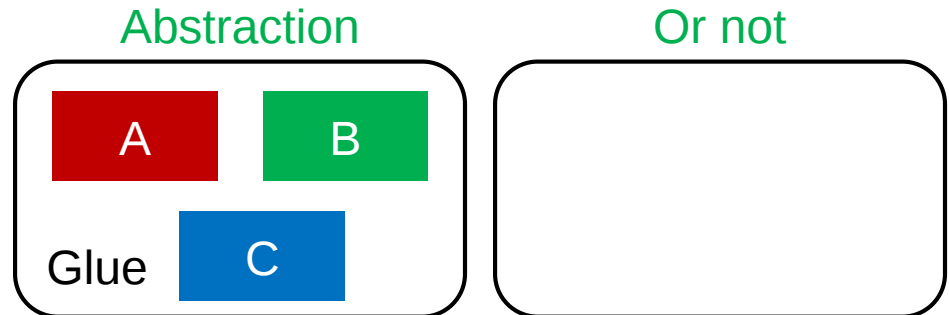
Later we use the syntax of C++
class to express an ADT

Pros of Data Abstraction & Encapsulation

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- **Simplification of software development (data abs)**
 - ▣ Facilitate the decomposition of a complex task into simpler ones
 - Do not need to know **how** other portions are implemented
- **Testing and debugging (data abs)**
 - ▣ Test and debug separately



- **Reusability (data abs & enc)**
- **Modifications to the representation of a data type (data enc)**
 - ▣ Implementation of a data type is invisible to the outside world
 - ▣ It can manipulate the data type only through a suite of operations
 - ▣ A change in the internal representation of a data type will not affect the rest of the program as long as the operations are kept the same
 - ▣ What if without data enc?

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Algorithm Specification

Algorithm . . .

Problem-solving
procedure

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□ **Definition:** An **algorithm** is

- A **finite** set of instructions that accomplishes a **particular task**

□ **Criteria:**

- **Input:** may have
- **Output:** must have

Task
(problem)

Procedure
(solution)

- **Definiteness:** must be clear and unambiguous
- **Finiteness:** terminate after a finite number of steps
- **Effectiveness:** must be basic and feasible with pencil and paper

□ **Cf. An **algorithm** is**

- A well-defined procedure for transforming some input to a desired output [Cormen et al. Introduction to Algorithms, 2nd Ed.]
- A well-defined procedure to solve a problem; a programmer turns the **algorithm** into a **computer program** [Sci-Tech Encyclopedia]
high-level ←-----→ low-level

Recap System Life Cycle

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□ Regard a large-scale computer program as a system

- Programming >> coding

1. Requirements

Problem

- Define specifications (input and output): vague → rigorous

2. Analysis

Algorithm

- Divide into manageable pieces: top-down vs. bottom-up

3. Design

- Determine data objects (abstract data types) and operations (algorithms): language-independent

4. Refinement and coding

Program

- Implement: language-dependent

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Selection Sort

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System life cycle:
requirements

□ Problem: **Sorting**

- Devise a program that sorts a collection of $n \geq 1$ integers
- **Input:** a sequence of n integers $\langle a_1, a_2, \dots, a_n \rangle$, $n \geq 1$
- **Output:** a permutation $\langle a'_1, a'_2, \dots, a'_n \rangle$ s.t. $a'_1 \leq a'_2 \leq \dots \leq a'_n$

System life cycle:
analysis & design

□ Solution: **Selection sort**

- From those integers that are currently unsorted, find the smallest and place it next in the sorted list. [in English]
- Well-defined? Clear? Unambiguous?
 - Where and how are the integers initially sorted?
 - Where to place the results?

Selection Sort

- Algorithm & Program

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Algorithm

System life cycle:
analysis & design

```
void SelectionSort (int *a, const int n)
{
    // Sort the  $n$  integers  $a[0]$  to  $a[n-1]$  into
    // nondecreasing order
    for (int  $i = 0$ ;  $i < n$ ;  $i++$ )
    {
        examine  $a[i]$  to  $a[n-1]$  and suppose
        the smallest integer is at  $a[j]$ ;
        interchange  $a[i]$  and  $a[j]$ ;
    }
}
```

High-level
Language independent

Program

System life cycle:
refinement & coding

```
void SelectionSort (int *a, const int n)
{
    // Sort the  $n$  integers  $a[0]$  to  $a[n-1]$  into
    // nondecreasing order
    for (int  $i = 0$ ;  $i < n$ ;  $i++$ )
    {
        int  $j = i$ ;
        // find smallest integer in  $a[i]$  to  $a[n-1]$ 
        for (int  $k = i + 1$ ;  $k < n$ ;  $k++$ )
            if ( $a[k] < a[j]$ )  $j = k$ ;
        swap( $a[i]$ ,  $a[j]$ );
    }
}
```

Low-level
Language dependent

7	4	1	9	2
1	4	7	9	2
1	2	7	9	4
1	2	4	9	7
1	2	4	7	9
1	2	4	7	9

Theorem: *SelectionSort*(a , n) correctly sorts a set of $n \geq 1$ integers; the result remains in $a[0] \dots a[n-1]$ such that $a[0] \leq a[1] \leq \dots \leq a[n-1]$.

Q: How to
prove it?

Binary Search

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□ Problem: Searching

▣ Input

- a sorted array of $n \geq 1$ distinct integers $a[0..n-1]$
- integer x

▣ Output

- return j , if there exists j such that $x = a[j]$
- return -1, otherwise

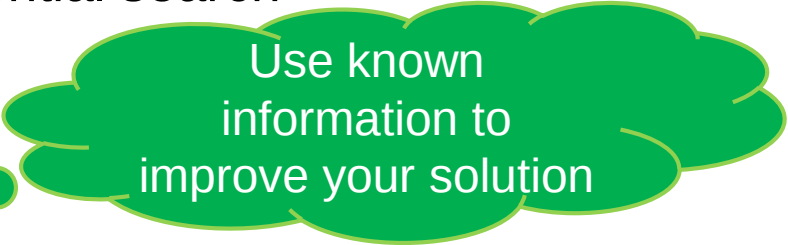
□ Solution:

▣ Compare one by one: Sequential search

- Correct but slow

▣ Better idea?

- Hint: **input is sorted** . . .
- **Divide-and-conquer: Binary search**



Use known
information to
improve your solution

Binary Search

- Divide-and-Conquer

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Divide-and-conquer paradigm

- **Divide** the problem into a number of subproblems
 - ▣ Similar but easier
- **Conquer** the subproblems
 - ▣ Solve them
- **Combine** the subsolutions to get the solution to the original problem

Binary search on a sorted array

- **Divide**: check the middle element
- **Conquer**: search the subarray
- **Combine**: trivial

0	5	13	19	22	41	55	68	72	81	98	<	55
						55	68	72	81	98	>	55
						55	68				=	55

Binary Search

- Algorithm & Program

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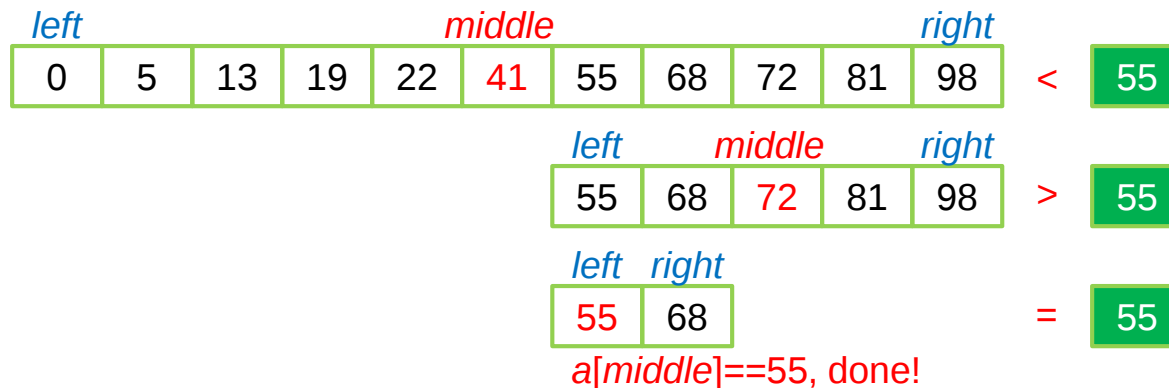
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Algorithm

```
int BinarySearch (int *a, const int x, const int n)
{
    // Search the sorted array a[0], ... , a[n-1] for x
    initialize left and right;
    while (there are more elements)
    {
        let middle be the middle element;
        if (x < a[middle]) set right to middle-1;
        else if (x > a[middle]) set left to middle+1;
        else return middle;
    }
    return -1; //not found
}
```

Program (Iterative)

```
int BinarySearch (int *a, const int x, const int n)
{
    // Search the sorted array a[0], ... , a[n-1] for x
    int left = 0, right = n-1;
    while (left <= right)
    {
        // there are more elements
        int middle = (left + right)/2;
        if (x < a[middle]) right = middle-1;
        else if (x > a[middle]) left = middle+1;
        else return middle;
    } //end of while
    return -1; //not found
}
```



- **Definition: A recursive function is**
 - ▣ A function that **invokes itself** before it is done
 - Direct (call by itself) vs. indirect (call through others)
- **Why to use recursion?**
 - ▣ Often can express a complex process very clearly
- **When to use recursion?**
 - ▣ The problem itself is recursively defined
 - e.g., factorials $n!$, Fibonacci sequence $F_n = F_{n-1} + F_{n-2}$
 - ▣ assignment+**if-else**+**while** $\Leftrightarrow$ assignment+**if-else**+**recursion**
 - ▣ e.g., **divide-and-conquer** approach
- **How to develop recursion?**
 1. Terminating condition (basis)
 - Trivial cases; directly computes the output
 2. Recursion (induction hypothesis)
 - If $n=k-1$, the statement holds, check $n=k$?

Binary Search

- Recursion

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Faster

More intuitive
and elegant

Program (Iterative)

```
int BinarySearch (int *a, const int x, const int n)
{ // Search the sorted array a[0], ... , a[n-1] for x
  int left = 0, right = n-1;
  while (left <= right)
  { // there are more elements
    int middle = (left + right)/2;
    if (x < a[middle]) right = middle-1;
    else if (x > a[middle]) left = middle+1;
    else return middle;
  } //end of while
  return -1; //not found
}
```

Program (Recursive)

```
int BinarySearch (int *a, const int x, const int
left, const int right)
{ // Search the sorted array a[left], ... , a[right] for x
  if (left <= right) {
    int middle = (left + right)/2;
    if (x < a[middle]) {
      return BinarySearch(a, x, left, middle-1);
    } else if (x > a[middle]) {
      return BinarySearch(a, x, middle+1, right);
    } else return middle;
  } //end of if
  return -1; //not found
}
```

Start with *BinarySearch(a, x, 0, n-1)*

Permutation Generator

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□ Problem:

- ▣ **Input:** a set of $n \geq 1$ elements
- ▣ **Output:** all possible permutations of this set
- ▣ e.g., input: $\{a,b,c\} \Rightarrow$ output: $\{(a,b,c), (a,c,b), (b,a,c), (b,c,a), (c,a,b), (c,b,a)\}$

□ Solution:

- ▣ Given $\{a,b,c\}$, the answer can be constructed by writing
 - a followed by all permutations of $\{b, c\}$
 - b followed by all permutations of $\{a, c\}$
 - c followed by all permutations of $\{a, b\}$
- ▣ If we can solve $n-1$ elements, we then can solve n elements

Permutation Generator

- Recursion

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```
void Permutations(char *a, const int k, const int m)
{
    // Generate all the permutations of a[k], ..., a[m]
    if (k == m) { // output permutation
        for (int i = 0; i <= m; i++) cout << a[i] << " ";
        cout << endl;
    }
    else // a[k:m] has more than one permutation. Generate these recursively.
        for (i = k; i <= m; i++) {
            swap(a[k], a[i]);
            Permutations(a, k+1, m);
            swap(a[k], a[i]);
        }
}
```

Start with *Permutations(a, 0, n-1)*

26 Performance Analysis and Measurement

Complexity

- **Definition:** The **space complexity** of a program is
 - ▣ The amount of memory it needs
 - ▣ $\Rightarrow$ **Storage requirements**
- **Definition:** The **time complexity** of a program is
 - ▣ The amount of computer time it needs
 - ▣ $\Rightarrow$ Computing time or **runtime**
- **Performance evaluation**
 - ▣ Performance analysis: a priori estimates
 - ▣ Performance measurement: a posteriori testing

Space Complexity

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- The space complexity $S(P)$ of a program P : $S(P) = c + S_P$
 - c : constant, including instruction space, space for simple variables and fixed-size component variables, space for constant
 - S_P : instance characteristics, e.g., the input size
 - Referenced variables, recursion stack space

```
float Abc(float a, float b, float c)
{
    return a + b + b*c + (a + b - c)/(a + b) + 4.0;
}
```

$$S_{Abc} = 0$$

```
float Sum(float *a, const int n)
{
    float s = 0;
    for (int i = 0; i < n; i++)
        s += a[i];
    return s;
}
```

$$S_{Sum}(n) = 0$$

```
float Rsum(float *a, const int n)
{
    if (n <= 0) return 0;
    else return (Rsum(a, n-1) + a[n-1]);
}
```

$$S_{Rsum}(n) = 4*(n+1)$$

Each call of *Rsum* requires 4 words for (1) value of *n*, (2) value of *a*, (3) returned value, and (4) return address

Time Complexity

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- **The time complexity $T(P)$ of a program P : $T(P) = t_p$**
 - ▣ t_p : instance characteristics
 - ▣ The number of program steps
 - A program step is a syntactically or semantically meaningful program segment whose execution time is **independent of the instance characteristics**.
 - ▣ $\Rightarrow$ We wish to know how the runtime increases as the number of inputs increases.
- **How to determine the **step count**?**
 - ▣ Method I: Introduce a new variable, **count**, into the program
 - ▣ Method II: Build a **step table**

Step Count

- Method I (1/2)

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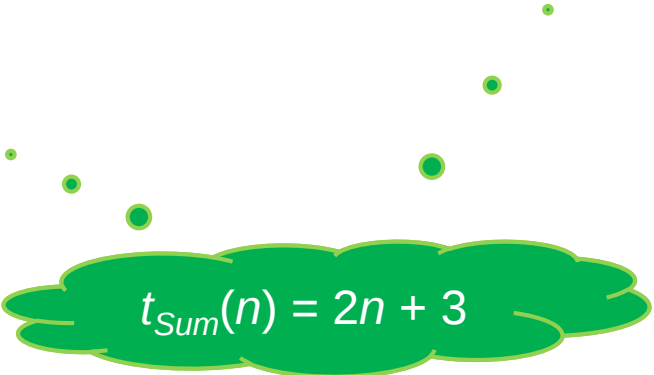
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Adding *count* into *Sum*

```
float Sum(float *a, const int n)
{
    float s = 0;
    count++; // count is global
    for (int i = 0; i < n; i++) {
        count++; // for for
        s += a[i];
        count++; // for assignment
    }
    count++; // for last time of for
    count++; // for return
    return s;
}
```

Simplified version with *count*

```
void Sum(float *a, const int n)
{
    for (int i = 0; i < n; i++)
        count += 2;
    count += 3;
}
```


$$t_{\text{Sum}}(n) = 2n + 3$$

Step Count

- Method I (2/2)

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Adding *count* into *Sum*

```
float Sum(float *a, const int n)
{
    float s = 0;
    count++; // count is global
    for (int i = 0; i < n; i++) {
        count++; // for for
        s += a[i];
        count++; // for assignment
    }
    count++; // for last time of for
    count++; // for return
    return s;
}
```

$$t_{\text{Sum}}(n) = 2n + 3$$

Adding *count* into *Rsum*

```
float Rsum(float *a, const int n)
{
    count++; // for if conditional
    if (n <= 0) {
        count++; // for return
        return 0;
    } else {
        count++; // for return
        return (Rsum(a, n-1) + a[n-1]);
    }
}
```

$$t_{\text{Rsum}}(n) = 2n + 2$$

$$\begin{aligned} t_{\text{Rsum}}(n) &= 2 + t_{\text{Rsum}}(n-1), t_{\text{Rsum}}(0)=2 \\ &= 2 + 2 + t_{\text{Rsum}}(n-2) \\ &= \dots = 2n + t_{\text{Rsum}}(0) \\ &= 2n + 2 \end{aligned}$$

Is *Rsum* faster?

Step Count

- Method II (1/2)

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Matrix addition

```
line void Add(int **a, int **b, int **c, int m, int n)
1  {
2      for (int i = 0; i < m; i++)
3          for (int j = 0; j < n; j++)
4              c[i][j] = a[i][j] + b[i][j];
5  }
```

Step table

line	s/e	frequency	total steps
1	0	1	0
2	1	m+1	m+1
3	1	m(n+1)	m(n+1)
4	1	mn	mn
5	0	1	0
total number of steps			2mn+2m+1

s/e: steps per execution
frequency: times executed

Step Count

- Method II (2/2)

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Adding *count* into *Sum*

```
float Sum(float *a, const int n)
1 {
2   float s = 0;
3   for (int i = 0; i < n; i++)
4     s += a[i];
5   return s;
6 }
```

Step table

line	s/e	frequency	total steps
1	0	1	0
2	1	1	1
3	1	$n+1$	$n+1$
4	1	n	n
5	1	1	1
6	0	1	0
total number of steps			$2n+3$

s/e: steps per execution
frequency: times executed

Is It Really that Simple?

- **Time complexity = step count**
 - ▣ A function of instance characteristics
- **Each of *Add*, *Sum*, *Rsum* has the same time complexity for all instances of the same n**
- **How about *BinarySearch*?**
 - ▣ Vary with the position of x in a
- **Typically, consider three kinds**
 - ▣ Best-case
 - ▣ Worst-case
 - ▣ Average-case

Asymptotic Notation

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- **Motivation:**

- To compare the time complexities of two programs that solve the same problem
- To predict the growth in runtime as the instance characteristics change

- **For the same problem, which is faster?**

- $T_A(n) = 100n+10$; $T_B(n) = 3n+3 \Rightarrow$ It depends!
 - Since the notion of a step count is itself inexact...
- $T_A(n) = 100n+10$; $T_B(n) = 3n^2+3 \Rightarrow A$ is faster for large n

Asymptotic Notation

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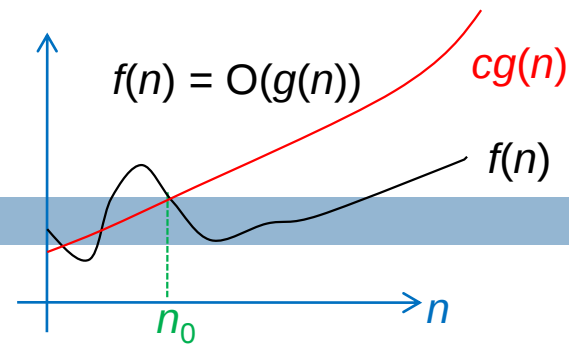
- **Types of bounding functions:**
 - ▣ O : upper bound
 - ▣ Ω : lower bound
 - ▣ Θ : tight bound

Asymptotic Notation

- Big Oh

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□ **Definition:** $f(n) = O(g(n))$ iff

- there exist **positive constants** c and n_0 such that $f(n) \leq cg(n)$ for all n , $n \geq n_0$
- $\Rightarrow g(n)$ is an **upper** bound of $f(n)$ if we ignore c and small n

□ **Example**

- $3n+2=O(n) \quad \Rightarrow \quad 3n+2 \leq 4n \text{ for } n \geq 2$
- $6 \cdot 2^n + n^2 = O(2^n) \quad \Rightarrow \quad 6 \cdot 2^n + n^2 \leq 7 \cdot 2^n \text{ for } n \geq 4$
- $3n+3=O(n^2) \quad \Rightarrow \quad 3n+3 \leq 3n^2 \text{ for } n \geq 2$

■ Correct but...

■ To be informative, $g(n)$ should be as small as possible

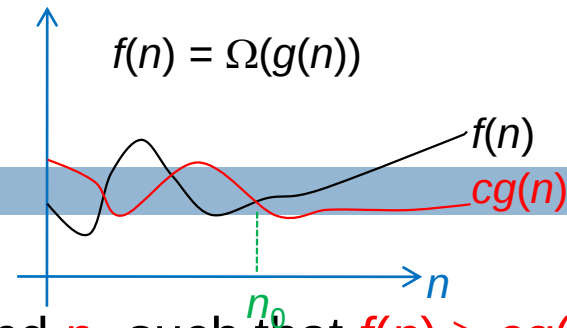
- Q: $3n^2 + n = O(n^2)$? **Yes**
- Q: $3n^2 + n = O(n)$? **No**
- Q: $3n^2 + n = O(n^3)$? **Yes**

Asymptotic Notation

- Omega

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□ **Definition:** $f(n) = \Omega(g(n))$ iff

- there exist **positive constants** c and n_0 such that $f(n) \geq cg(n)$ for all n , $n \geq n_0$
- $\Rightarrow g(n)$ is a **lower** bound of $f(n)$ if we ignore c and small n
- To be informative, $g(n)$ should be as large as possible

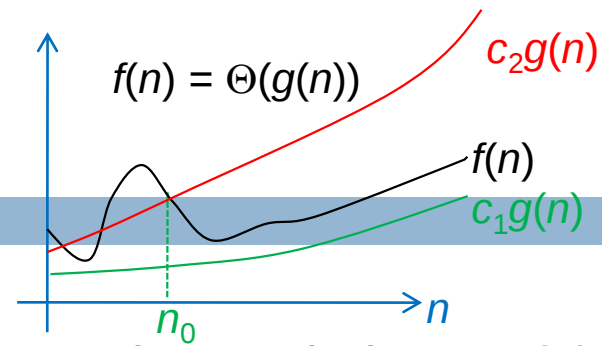
□ **Example:**

- Q: $3n^2 + n = \Omega(n^2)$? **Yes**
- Q: $3n^2 + n = \Omega(n)$? **Yes**
- Q: $3n^2 + n = \Omega(n^3)$? **No**

Asymptotic Notation

- Theta

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□ **Definition:** $f(n) = \Theta(g(n))$ iff

- there exist **positive constants** c_1, c_2 and n_0 such that $c_1g(n) \leq f(n) \leq c_2g(n)$ for all $n, n \geq n_0$
- $\Rightarrow g(n)$ is a **tight** bound of $f(n)$ if we ignore c_1, c_2 and small n

□ **Example**

- Q: $3n^2 + n = \Theta(n^2)$? **Yes**
- Q: $3n^2 + n = \Theta(n)$? **No**
- Q: $3n^2 + n = \Theta(n^3)$? **No**

Polynomial-Time Complexity

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Polynomial-time complexity $O(p(n))$

- ▣ n is the input size
- ▣ $p(n)$ is a **polynomial** function of n ($p(n) = n^{O(1)}$)

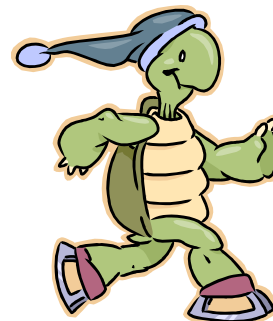
Order

- ▣ $O(1)$: constant
- ▣ $O(\log n)$: logarithmic
- ▣ $O(n^{0.5})$: sublinear
- ▣ $O(n)$: linear
- ▣ $O(n \log n)$: loglinear
- ▣ $O(n^2)$: quadratic
- ▣ $O(n^3)$: cubic
- ▣ $O(n^4)$: quartic
- ▣ $O(2^n)$: exponential
- ▣ $O(n!)$: factorial
- ▣ $O(n^n)$

Faster



Slower



Function Growth

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Function values

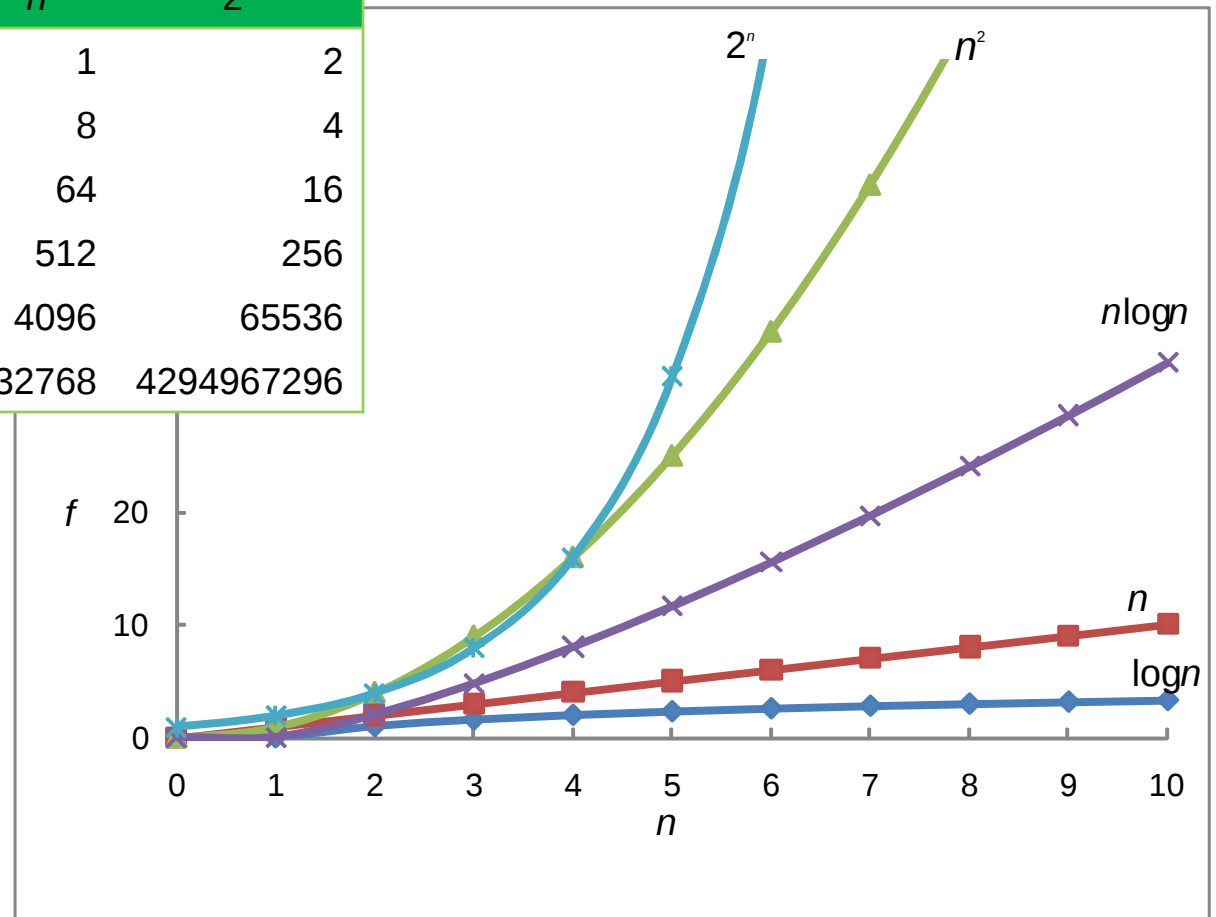
$\log n$	n	$n \log n$	n^2	n^3	2^n
0	1	0	1	1	2
1	2	2	4	8	4
2	4	8	16	64	16
3	8	24	64	512	256
4	16	64	256	4096	65536
5	32	160	1024	32768	4294967296

$\log = \log_{10}$

$\lg = \log_2$

$\ln = \log_e$

Predicted curves



Time on a 1-billion-steps-per-sec Computer

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n	$f(n)$						
	n	$n \log_2 n$	n^2	n^3	n^4	n^{10}	2^n
10	.01 μ s	.03 μ s	.1 μ s	1 μ s	10 μ s	10s	1 μ s
20	.02 μ s	.09 μ s	.4 μ s	8 μ s	160 μ s	2.84h	1ms
30	.03 μ s	.15 μ s	.9 μ s	27 μ s	810 μ s	6.83d	1s
40	.04 μ s	.21 μ s	1.6 μ s	64 μ s	2.56ms	121d	13d
50	.05 μ s	.28 μ s	2.5 μ s	125 μ s	6.25ms	3.1y	$4 \cdot 10^{13}$ y
100	.10 μ s	.66 μ s	10 μ s	1ms	100ms	3171y	$32 \cdot 10^{283}$ y
10^3	1 μ s	9.96 μ s	1 ms	1s	115.7d	$3.17 \cdot 10^{13}$ y	
10^4	10 μ s	130 μ s	100 ms	11.57d	3171y	$3.17 \cdot 10^{23}$ y	
10^5	100 μ s	1.66 ms	10s	31.71y	$3.17 \cdot 10^7$ y	$3.17 \cdot 10^{33}$ y	
10^6	1ms	19.92ms				$3.17 \cdot 10^{43}$ y	

$\mu = 10^{-6}$ $m = 10^{-3}$

s = sec m = min h = hour d = day y = year

Performance Measurement

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Analysis vs. measurement

□ Sequential search

1. Time complexity: $\Theta(n)$
2. Real runtime can be measured by *time()* in C++

1. Asymptotic analysis

- Works only for **sufficiently large** values of n
- Forgets coefficients

2. The measured time plot

- May not lie exactly on the predicted curve due to the effects of **low-order terms**

Time plot of sequential search

